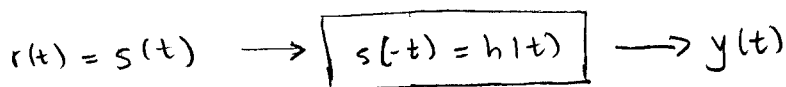


Problem 1

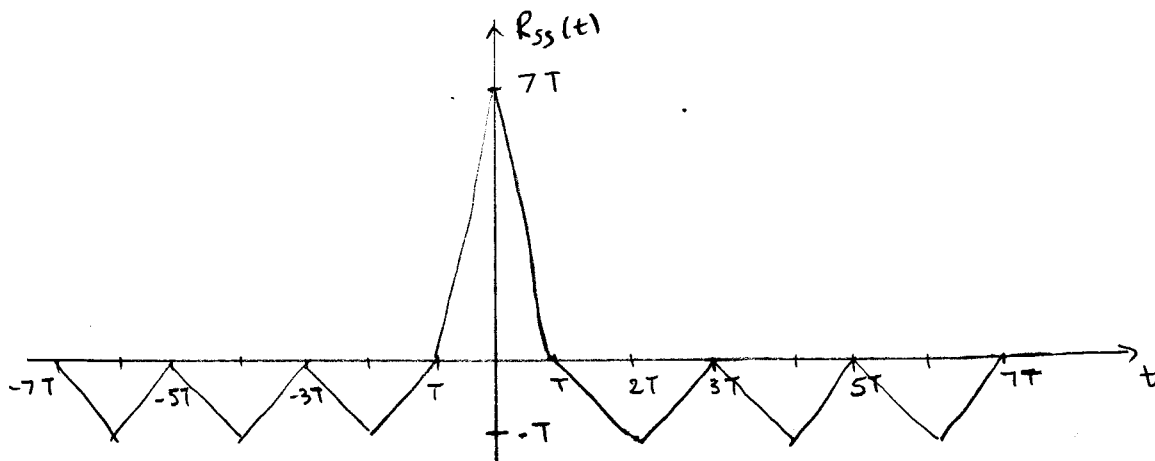
a) let $T_d = 0$, $r(t) = s(t)$ where $s(t)$ is given in Figure 1(a).

Then we have the following block diagram



$$\begin{aligned} \text{thus, } y(t) &= s(t) * h(t) = \int_{-\infty}^{\infty} s(\tau) h(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} s(\tau) s(\tau-t) d\tau = R_{ss}(t) \end{aligned}$$

So the output is the autocorrelation of $s(t)$. The resulting $y(t)$ is shown below



If T_d is non zero then $r(t) = s(t - T_d)$ and

$$y(t) = s(t - T_d) * s(-t) = \int_{-\infty}^{\infty} s(\tau - T_d) s(\tau - t) d\tau$$

$$\stackrel{\tau - T_d = v}{=} \int_{-\infty}^{\infty} s(v) s(v - (t - T_d)) dv = R_{ss}(t - T_d)$$

So the output is time-shifted by T_d as we should expect. The max will appear at $t = T_d$.

Therefore an algorithm estimating the range of a target could be the following;

- 1) find time corresponding to the max value of the output of the filter which is T_d (2-way travel time)
- 2) range is : $R = \frac{c \cdot T_d}{2}$ (1-way travel time)

where c is the speed in the propagation medium.

b) If $h(t) = s(\underbrace{\tau T}_{\text{delay}} - t)$ then the output becomes

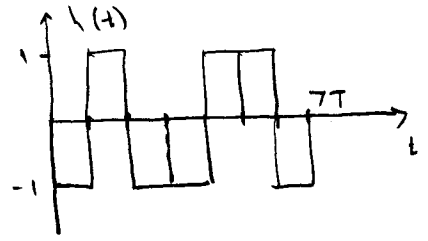
$$y(t) = s(t - T_d) + s(-(t - \tau T)) = \int_{-\infty}^{\infty} s(z - T_d) s(-z + \tau T - t) dz$$

$$\stackrel{v = z - T_d}{=} \int_{-\infty}^{\infty} s(v) s(v - (t - T_d + \tau T)) dv = R_{ss}(t - (\tau T + T_d))$$

so the output is time shifted by $\tau T + T_d$ as expected. The max value is at $\tau T + T_d$ so the two-way travel time is $T_d - \tau T$.

and the range is $R = c \cdot \frac{t_m}{2} = \frac{c \cdot (T_d - \tau T)}{2}$.

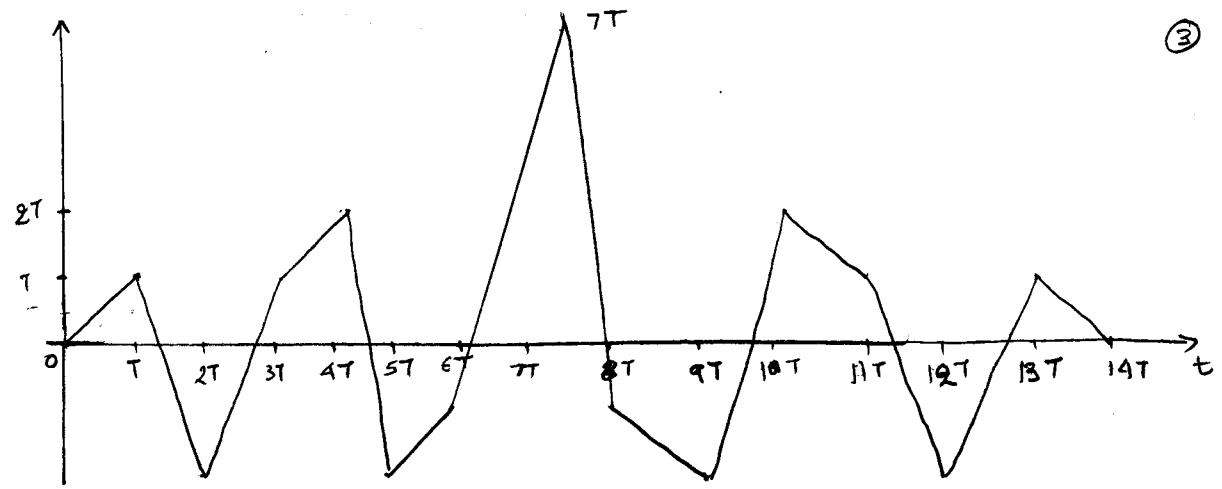
c) the matched filter impulse response for this input is



$$h(t) = s(\tau T - t)$$

the output $y(t) = \int_{-\infty}^{\infty} s(z) s(z - (t - \tau T)) dz$ is

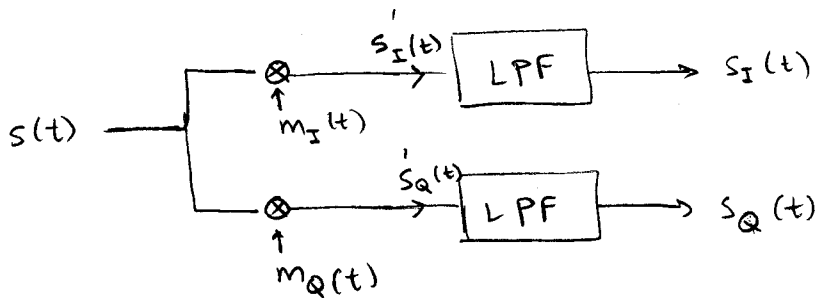
③



Obviously, if we reverse one bit in the Barker code the output of the filter has bigger sidelobes hence we are more vulnerable in making a mistake in high noise conditions.

Problem 2

- a) From the given scheme we realize that the incoming narrowband signal $s(t)$ is being demodulated by a train of pulses.

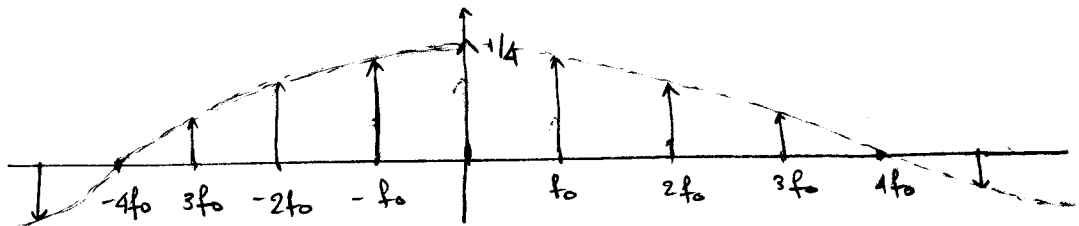


It is easier if we do the analysis in the frequency domain. $m_I(t)$ is a train of pulses so it can be written as:

$$m_I(t) = \text{rect}\left(\frac{t}{T}\right) * \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

The F.T. of $m_I(t)$ is then:

$$\begin{aligned} M_I(f) &= \frac{T}{4} \cdot \text{sinc}\left(\pi f \frac{T}{4}\right) \cdot \frac{1}{T} \sum_{k=-\infty}^{\infty} \delta\left(f - \frac{k}{T}\right) = \\ &= \frac{1}{4} \sum_{k=-\infty}^{\infty} \text{sinc}\left(\pi f \frac{T}{4}\right) \delta\left(f - \frac{k}{T}\right) = \\ &= \frac{1}{4} \sum_{k=-\infty}^{\infty} \text{sinc}\left(\frac{\pi k T}{4}\right) \delta\left(f - \frac{k}{T}\right) = \\ & \stackrel{T = \frac{1}{f_0}}{=} \sum_{k=-\infty}^{\infty} \frac{1}{4} \text{sinc}\left(\frac{\pi k}{4}\right) \delta\left(f - k f_0\right) \end{aligned}$$



Hence $S'_I(t) = s(t) \cdot m_I(t) \Rightarrow$

$$S'_I(f) = S(f) * M_I(f) = S(f) * \sum_{k=-\infty}^{\infty} \frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right) \delta(f - kf_0)$$

$$= \sum_{k=-\infty}^{\infty} \frac{\frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right)}{\text{weights}} S(f - kf_0)$$

Thus the spectrum $S'_I(f)$ is a weighted superposition of shifted spectrums $S(f \pm kf_0)$, $k=0, \pm 1, \pm 2, \dots$

Substituting $S(f) = S_0(f - f_0) + S_0^*(-(f + f_0))$ we have

$$S'_I(f) = \sum_{k=-\infty}^{\infty} \frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right) \left[S_0(f - (k+1)f_0) + S_0^*(-(f - (k-1)f_0)) \right]$$

After lowpass filtering only the baseband components survive i.e.

| | |
|-----------------|-----------------------------------|
| for $k=1$ only | $S_0^*(-(f - (k-1)f_0))$ survives |
| for $k=-1$ only | $S_0(f - (k+1)f_0)$ survives |

$$\text{Thus, } S_I(f) = \frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right) (S_0(f) + S_0^*(-f)) =$$

$$= \frac{\sqrt{2}}{4} \cdot \underline{\underline{\text{Even}(S_0(f))}}$$

Similarly

$$m_Q(t) = m_I\left(t - \frac{T}{4}\right) \Rightarrow M_Q(f) = M_I(f) e^{-j2\pi f \frac{T}{4}} =$$

$$= \sum_{k=-\infty}^{\infty} \frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right) \delta(f - kf_0) e^{-j2\pi f \frac{T}{4}} =$$

$$= \sum_{k=-\infty}^{\infty} \frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right) e^{-j2\pi k f_0 \frac{T}{4}} \delta(f - kf_0)$$

$$= \sum_{k=-\infty}^{\infty} \frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right) \underbrace{e^{-j k \frac{\pi}{2}}}_{j^{-k}} \delta(f - kf_0) = \sum_{k=-\infty}^{\infty} j^{-k} \frac{1}{4} \text{sinc}\left(\frac{kT}{4}\right) \delta(f - kf_0)$$

Hence, $S'_Q(f) = \sum_{k=-\infty}^{\infty} j^{-k} \frac{1}{4} \text{sinc}\left(\frac{kD}{4}\right) S_0(f - (k+1)f_0) + S_0^*(-(f - (k-1)f_0))$

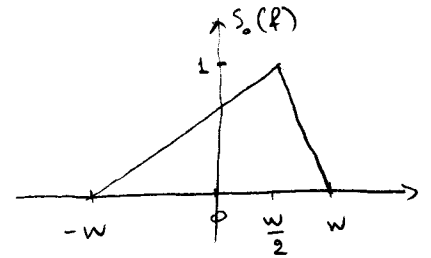
for the same reason as before only $S_0(f)$ ($k=-1$) and $S_0^*(-f)$ ($k=1$) survive so:

$$S_a(f) = j \frac{1}{4} \text{sinc}\left(\frac{kD}{4}\right) S_0(f) - j \frac{1}{4} \text{sinc}\left(\frac{kD}{4}\right) S_0^*(-f)$$

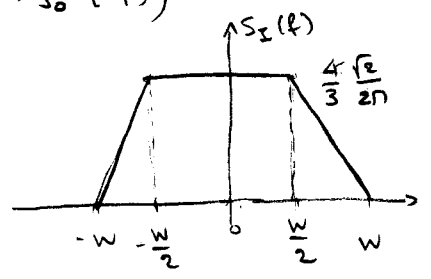
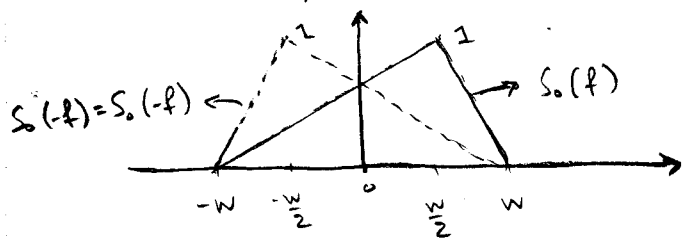
$$= \frac{\sqrt{2}}{\pi} j \left(\frac{S_0(f) - S_0^*(-f)}{2} \right) = \frac{\sqrt{2}}{\pi} j \text{Odd}(S_0(f))$$

$S_I(f), S_a(f)$ fit definition of quadrature demodulation.

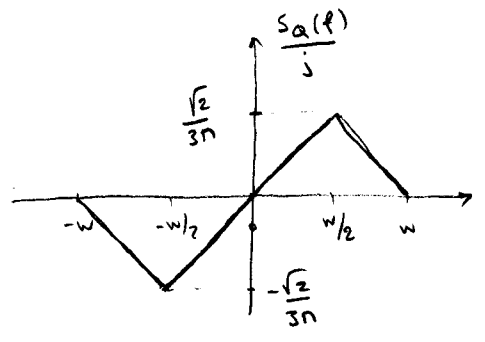
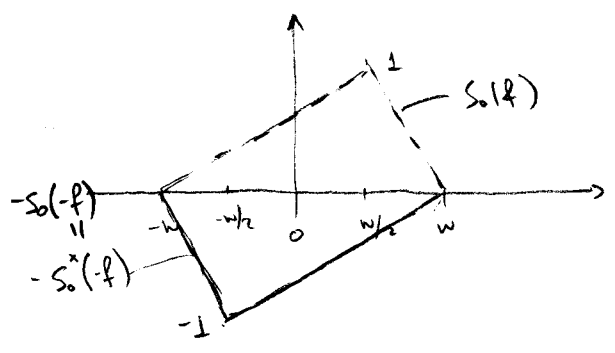
b) $S_0(f) = \begin{cases} \frac{2}{3W}(f+W) & -W < f \leq W/2 \\ -\frac{2}{3W}(f-W) & W/2 < f \leq W \end{cases}$



$S_I(f) = \frac{\sqrt{2}}{\pi} \text{Even}[S_0(f)] = \frac{\sqrt{2}}{2\pi} (S_0(f) + S_0^*(-f))$



$S_a(f) = \frac{\sqrt{2}}{\pi} j \text{odd}[S_0(f)] = j \frac{\sqrt{2}}{2\pi} (S_0(f) - S_0^*(-f))$



Problem 3

a) In general, if $g(x, y)$ and $h(x, y)$ are continuous and differentiable functions then the joint pdf of $z = g(x, y)$ and $w = h(x, y)$ is derived by following three steps:

a) solve system: $\left. \begin{matrix} g(x, y) = z \\ h(x, y) = w \end{matrix} \right\} \Rightarrow \begin{matrix} x_i = \bar{g}_i(z, w) \quad i=1 \dots n \\ y_i = \bar{h}_i(z, w) \end{matrix}$

b) find Jacobian $J_i(z, w) = \begin{vmatrix} \frac{\partial \bar{g}_i}{\partial z} & \frac{\partial \bar{g}_i}{\partial w} \\ \frac{\partial \bar{h}_i}{\partial z} & \frac{\partial \bar{h}_i}{\partial w} \end{vmatrix}$ for each i

c) $f_{z,w}(z, w) = \sum_{i=1}^n \left(f_{x,y}(\bar{g}_i(z, w), \bar{h}_i(z, w)) \cdot |J_i(z, w)| \right)$
↑
abs. value

In our case: $r = \sqrt{x_1^2 + x_2^2} = g(x_1, x_2)$
 $\theta = \tan^{-1}\left(\frac{x_2}{x_1}\right) = h(x_1, x_2)$

Obviously the system $\begin{cases} r = \sqrt{x_1^2 + x_2^2} \\ \theta = \tan^{-1}\left(\frac{x_2}{x_1}\right) \end{cases}$ has only

one solution: $x_1 = r \cos \theta = \bar{g}(r, \theta)$
 $x_2 = r \sin \theta = \bar{h}(r, \theta)$

when $\theta \in (-\pi, \pi)$.

The Jacobian is $J(z, w) = \begin{vmatrix} \frac{\partial r \cos \theta}{\partial r} & \frac{\partial r \cos \theta}{\partial \theta} \\ \frac{\partial r \sin \theta}{\partial r} & \frac{\partial r \sin \theta}{\partial \theta} \end{vmatrix} =$
 $= \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r$

Thus, $f_{r,\theta} = r \cdot f_{x,y}(r \cos \theta, r \sin \theta)$

we know that x_1, x_2 are iid $N(0, \sigma^2)$ so

$$f_{x_1, x_2}(x_1, x_2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x_1^2}{2\sigma^2}} \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x_2^2}{2\sigma^2}} = \frac{1}{2\pi\sigma^2} e^{-\frac{x_1^2 + x_2^2}{2\sigma^2}} \quad x_1, x_2 \in \mathbb{R}$$

thus, $f_{r, \theta}(r, \theta) = \begin{cases} \frac{r}{2\pi\sigma^2} e^{-\frac{r^2}{2\sigma^2}}, & r \geq 0 \\ & \theta \in (-\pi, \pi) \\ 0, & \text{o.w.} \end{cases}$

$$f_r(r) = \int_{-\pi}^{\pi} \frac{r e^{-r^2/2\sigma^2}}{2\pi\sigma^2} d\theta = \frac{r e^{-r^2/2\sigma^2}}{\sigma^2}, \quad r \geq 0 \quad (\text{Rayleigh dist.})$$

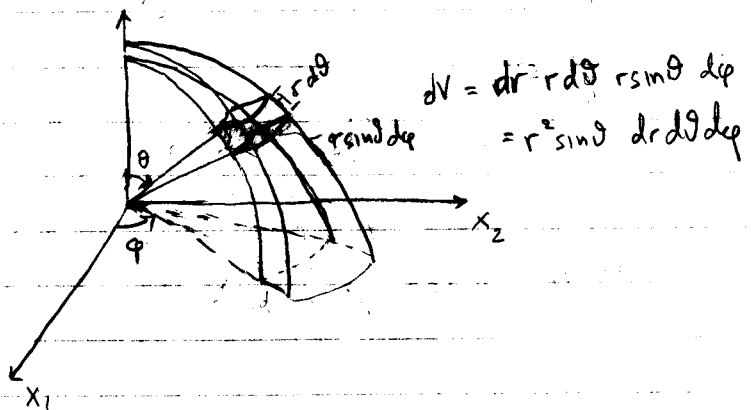
$$f_\theta(\theta) = \int_0^\infty \frac{r}{2\pi\sigma^2} e^{-r^2/2\sigma^2} dr = \frac{1}{2\pi} e^{-r^2/2\sigma^2} \Big|_0^\infty = \frac{1}{2\pi}, \quad \theta \in (-\pi, \pi) \quad (\text{Uniform dist.})$$

Note that $f_{r, \theta}(r, \theta) = \frac{1}{2\pi} \cdot \frac{r}{\sigma^2} e^{-r^2/2\sigma^2} = f_\theta(\theta) f_r(r)$

so r, θ are independent !!

b) Generalizing to 3-D where

$$\begin{aligned} r &= \sqrt{x_1^2 + x_2^2 + x_3^2} & x_1 &= r \sin\theta \cos\varphi, & r &\geq 0 \\ \theta &= \tan^{-1}(\sqrt{x_1^2 + x_2^2}/x_3) & \Rightarrow & x_2 &= r \sin\theta \sin\varphi, & \theta &\in (0, \pi) \\ \varphi &= \tan^{-1}(x_2/x_1) & & x_3 &= r \cos\theta, & \varphi &\in (0, 2\pi) \end{aligned}$$



$$f(r, \theta, \phi) = \begin{vmatrix} \frac{\partial r \sin \theta \cos \phi}{\partial r} & \frac{\partial r \sin \theta \cos \phi}{\partial \theta} & \frac{\partial r \sin \theta \cos \phi}{\partial \phi} \\ \frac{\partial r \sin \theta \sin \phi}{\partial r} & \frac{\partial r \sin \theta \sin \phi}{\partial \theta} & \frac{\partial r \sin \theta \sin \phi}{\partial \phi} \\ \frac{\partial r \cos \theta}{\partial r} & \frac{\partial r \cos \theta}{\partial \theta} & \frac{\partial r \cos \theta}{\partial \phi} \end{vmatrix} =$$

$$= \begin{vmatrix} \sin \theta \cos \phi & -r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{vmatrix} = -r^2 \sin \theta$$

since $f_{x_1, x_2, x_3}(x_1, x_2, x_3) = \frac{1}{(2\pi\sigma^2)^{3/2}} e^{-\frac{x_1^2 + x_2^2 + x_3^2}{2\sigma^2}}$

we have:

$$f_{r, \theta, \phi}(r, \theta, \phi) = \frac{r^2 \sin \theta}{(2\pi\sigma^2)^{3/2}} e^{-r^2/2\sigma^2} \quad \begin{matrix} r \geq 0 \\ \theta \in (0, \pi) \\ \phi \in (0, 2\pi) \end{matrix}$$

The marginal distributions are:

$$f_r(r) = \int_0^{2\pi} \int_0^\pi \frac{r^2 \sin \theta}{(2\pi\sigma^2)^{3/2}} e^{-r^2/2\sigma^2} d\phi d\theta = \sqrt{\frac{2}{\pi}} \frac{r^2}{\sigma^3} e^{-r^2/2\sigma^2}, \quad r > 0$$

$$f_\theta(\theta) = \int_0^{2\pi} \int_0^\infty \frac{r^2 \sin \theta}{(2\pi\sigma^2)^{3/2}} e^{-r^2/2\sigma^2} dr d\phi =$$

$$= \frac{\sin \theta}{\sqrt{2\pi}\sigma^3} \int_0^\infty r^2 e^{-r^2/2\sigma^2} dr = \frac{\sin \theta}{2} \quad \theta \in (0, \pi)$$

integration by part
 $r^2 e^{-r^2/2\sigma^2} = r \cdot (-e^{-r^2/2\sigma^2}) \cdot \sigma^2$

$$f_\phi(\phi) = \int_0^\infty \int_0^\pi \frac{r^2 \sin \theta}{(2\pi\sigma^2)^{3/2}} e^{-r^2/2\sigma^2} d\theta dr = \int_0^\infty \frac{r^2 e^{-r^2/2\sigma^2}}{(2\pi\sigma^2)^{3/2}} dr =$$

$$= \frac{1}{2\pi} \quad \phi \in (0, 2\pi)$$

Note that $f_{r\theta\phi}(r, \theta, \phi) = f_r(r) f_\theta(\theta) f_\phi(\phi)$
so r, θ, ϕ are statistically independent.

A chi-square random variable is related to a Gaussian r.v. by the following transformation

$$Y = \sum_{i=1}^n X_i^2 \quad \text{where } X_i \text{ iid} \sim N(0, \sigma^2)$$

We say that Y is central chi-square distributed with n degrees of freedom.

We know the pdf of $\sqrt{Y} = r = \sqrt{X_1^2 + X_2^2 + X_3^2}$ and we want to relate it with the pdf of Y ($n=3$).

We have $Y = r^2 = g(r)$ which has unique solution $r = \sqrt{Y}$.

Using the general formula

$$f_Y(y) = \sum_{i=1}^n \frac{f_r(r_i)}{|g'(r_i)|} \quad \text{we have:}$$

$$f_Y(y) = \frac{f_r(r)}{2r} \Big|_{r=\sqrt{y}} = \frac{1}{2} \frac{\sqrt{2}}{\sqrt{\pi}} \frac{y e^{-y/2\sigma^2}}{\sigma^2 \sqrt{y}} = \frac{y^{1/2} e^{-y/2\sigma^2}}{\sqrt{\frac{\pi}{2}} \sigma^2}$$

so $f_r(r) = 2r f_Y(r^2)$

χ^2 pdf with 3 d.o.f.

where $Y \sim \chi^2$ with 3 d.o.f.

Interpretation of $f_\theta(\theta)$: In cartesian coordinates if you fix the distance $r = \sqrt{x_1^2 + x_2^2 + x_3^2}$ then $f_{x_1 x_2 x_3}$ is constant no matter the altitude. In polar coordinates if you fix r then $f_{r\theta\phi}$ depends on the altitude (varies as $\sin^2 \theta$).

c) if we consider $x_1 \sim N(m \cos \varphi_m, \sigma^2)$

and $x_2 \sim N(m \sin \varphi_m, \sigma^2)$ then the joint density of x_1, x_2 is:

$$f_{x_1, x_2}(x_1, x_2) = \frac{1}{2\pi\sigma^2} e^{-\frac{(x_1 - m \cos \varphi_m)^2}{2\sigma^2}} e^{-\frac{(x_2 - m \sin \varphi_m)^2}{2\sigma^2}}$$

$$= \frac{1}{2\pi\sigma^2} e^{-\frac{(x_1^2 + x_2^2 - 2x_1 \cos \varphi_m - 2x_2 \sin \varphi_m + m^2)}{2\sigma^2}}$$

we have $x_1 = r \cos \theta$, $x_2 = r \sin \theta$ and we are seeking the joint pdf of r, θ .

Following the same procedure as in part (a) we get:

$$f_{r, \theta}(r, \theta) = r \cdot f_{x_1, x_2}(r \cos \theta, r \sin \theta) =$$

$$= \frac{r}{2\pi\sigma^2} e^{-\frac{(r^2 + m^2 - 2rm \cos(\theta - \varphi_m))}{2\sigma^2}}$$

$r \geq 0$
 $\theta \in (-\pi, \pi)$

The marginal densities are:

$$f_r(r) = \int_{-\pi}^{\pi} \frac{r}{2\pi\sigma^2} e^{-\frac{(r^2 + m^2 - 2rm \cos(\theta - \varphi_m))}{2\sigma^2}} d\theta$$

$$= \frac{r}{2\pi\sigma^2} e^{-\frac{r^2 + m^2}{2\sigma^2}} \int_{-\pi}^{\pi} e^{\frac{rm \cos(\theta - \varphi_m)}{\sigma^2}} d\theta$$

$$= \frac{r}{2\pi\sigma^2} e^{-\frac{r^2 + m^2}{2\sigma^2}} \int_0^{2\pi} e^{\frac{rm \cos(\theta - \varphi_m + \pi)}{\sigma^2}} d\theta =$$

$$= \frac{r}{2\pi\sigma^2} e^{-\frac{r^2 + m^2}{2\sigma^2}} \int_0^{2\pi} e^{\frac{rm \cos(\theta - \varphi_m)}{\sigma^2}} d\theta$$

$$= \frac{r}{\sigma^2} \cdot e^{-\frac{(r^2 + m^2)}{2\sigma^2}} I_0\left(\frac{rm}{\sigma^2}\right), \quad r \geq 0$$

(note that $f_r(r)$ doesn't depend on φ_m).

where we identify the integral

$$I_0(x) = \frac{1}{2\pi} \int_0^{2\pi} e^{x \cos(\theta - \varphi)} d\theta$$

as the modified Bessel function of the 1st kind and zeroth order.

$$f_{\theta}(\theta) = \int_0^{\infty} \frac{r}{2\pi\sigma^2} e^{-\frac{(r^2 + m^2 - 2rm \cos(\theta - \varphi_m))}{2\sigma^2}} dr$$

complete the square to obtain

$$\begin{aligned} f_{\theta}(\theta) &= \int_0^{\infty} \frac{r}{2\pi\sigma^2} e^{-\frac{1}{2\sigma^2}(r - m \cos(\theta - \varphi_m))^2} e^{-\frac{m^2}{2\sigma^2}(1 - \cos^2(\theta - \varphi_m))} dr \\ &= \frac{e^{-\frac{m^2 \sin^2(\theta - \varphi_m)}{2\sigma^2}}}{2\pi\sigma^2} \int_0^{\infty} r e^{-\frac{(r - m \cos(\theta - \varphi_m))^2}{2\sigma^2}} dr \end{aligned}$$

doing integration by parts and identifying

that

$$\text{erf}(x) = \int_0^x e^{-t^2} dt \quad (\text{called the "error function"})$$

we have the final result:

$$f_{\theta}(\theta) = \frac{e^{-\frac{m^2 \sin^2(\theta - \varphi_m)}{2\sigma^2}}}{2\pi\sigma^2} \left[\sigma^2 e^{-\frac{m^2 \cos^2(\theta - \varphi_m)}{2\sigma^2}} + \sqrt{\frac{\pi}{2}} \sigma m \cos(\theta - \varphi_m) \cdot \left(1 - \text{erf}\left(\frac{-m \cos(\theta - \varphi_m)}{\sqrt{2}\sigma}\right)\right) \right]$$

d) if we assume φ_m is random then in part (c) all the densities we found are conditioned with respect to φ_m . Hence, we know $f_{r|\varphi_m}(r)$ and we are looking for $f_r(r)$.

Invoking total probability thm we have.

(7)

$$f_r(r) = \int_0^{2\pi} f_{r/q_m}(r) f_{q_m}(q) dq =$$

$$= \int_0^{2\pi} \frac{r}{\sigma^2} e^{-\frac{(r^2+m^2)}{2\sigma^2}} I_0\left(\frac{rm}{\sigma^2}\right) \frac{1}{2\pi} dq =$$

$$= \frac{r}{\sigma^2} e^{-\frac{(r^2+m^2)}{2\sigma^2}} I_0\left(\frac{rm}{\sigma^2}\right)$$

Since $f_{r/q_m}(r) = f_r(r)$

then r is independent of q_m !

Problem 4

①

$$a) \quad H(f) = \frac{A}{R} e^{-j \operatorname{sgn}(f) (2\pi f)^2 \frac{R}{g}}$$

note that A is complex $\Rightarrow A = |A| e^{j\varphi}$
 thus the phase of the transfer function is:

$$\angle H(f) = \varphi - \operatorname{sgn}(f) (2\pi f)^2 \frac{R}{g}$$

phase delay: $T_p(f) \triangleq -\frac{1}{2\pi f} \angle H(f) = \frac{-\varphi + \operatorname{sgn}(f) (2\pi f)^2 \frac{R}{g}}{2\pi f}$

group delay: $T_g(f) \triangleq -\frac{1}{2\pi} \frac{d \angle H(f)}{df} =$

$$= \frac{1}{2\pi} \left(\operatorname{sgn}(f)' (2\pi f)^2 \frac{R}{g} + \operatorname{sgn}(f) 4\pi f \cdot 2\pi \frac{R}{g} \right)$$

$$\operatorname{sgn}'(f) = 2\delta(f)$$

$$= \frac{1}{2\pi} \cdot \underbrace{2\delta(f)}_0 (2\pi f)^2 \frac{R}{g} + \operatorname{sgn}(f) 2\pi f \frac{R}{g}$$

$$= \operatorname{sgn}(f) 4\pi f \frac{R}{g}$$

b) from lecture in order for dispersion to be small $n\beta(f)W^2 \leq \frac{n}{4}$ where $\beta(f) = \text{dispersion}$.

$$\beta(f) \triangleq -\frac{1}{2\pi} \frac{d^2 \angle H(f)}{df^2} = \frac{1}{2\pi} \left(\operatorname{sgn}(f) 8\pi^2 f \frac{R}{g} \right)'$$

$$= \frac{1}{2\pi} \left(\underbrace{2\delta(f)}_0 4\pi f \frac{R}{g} + \operatorname{sgn}(f) 8\pi^2 \frac{R}{g} \right) = 4\pi \operatorname{sgn}(f) \frac{R}{g}$$

So the condition is $2 \operatorname{sgn}(f) \frac{R}{g} W^2 \leq \frac{1}{4} \Rightarrow f \geq 0$

$$W^2 \leq \frac{1}{16\pi} \frac{g}{R} \Rightarrow W \leq \left(\frac{g}{16\pi R} \right)^{1/2}$$

so bandwidth is inversely proportional to $R^{1/2}$.

$$\begin{aligned}
 c) \quad x(t) &= c e^{-\kappa t} (t \cos(2\pi f_0 t) - \sin(2\pi f_0 t)) u(t) \\
 &= c e^{-\kappa t} (t \cdot \cos(2\pi f_0 t) - 1 \cdot \sin(2\pi f_0 t)) u(t) \\
 &= c e^{-\kappa t} \operatorname{Re} \left[(t+j) \cos(2\pi f_0 t) + j \sin(2\pi f_0 t) \right] u(t) = \\
 &= 2 \operatorname{Re} \left[\frac{c}{2} e^{-\kappa t} (t+j) u(t) e^{j 2\pi f_0 t} \right] \Rightarrow \tilde{x}_0(t) = \frac{c}{2} e^{-\kappa t} (t+j) u(t)
 \end{aligned}$$

following the convention $\int |\tilde{x}(t)|^2 dt = 1 \Rightarrow$

$$\int_{-\infty}^{\infty} \frac{c^2}{4} e^{-2\kappa t} (t^2+1) u^2(t) dt = 1 \Rightarrow \frac{c^2}{4} \int_0^{\infty} e^{-2\kappa t} (t^2+1) dt = 1$$

$$\rightarrow c = \sqrt{\frac{16 \kappa^3}{1+2\kappa^2}}$$

$$\begin{aligned}
 X_0(f) &= \mathcal{F} \left\{ \frac{c}{2} e^{-\kappa t} (t+j) u(t) \right\} = \\
 &= \frac{c}{2} \left[\mathcal{F} \left\{ e^{-\kappa t} t u(t) \right\} + j \mathcal{F} \left\{ e^{-\kappa t} u(t) \right\} \right] \\
 &= \frac{c/2}{(\kappa + j 2\pi f)^2} + \frac{j c/2}{\kappa + j 2\pi f}
 \end{aligned}$$

d) neglecting dispersion, the complex envelope of the output is:

$$\begin{aligned}
 \tilde{y}_0(t) &= |H(f_0)| e^{-j 2\pi f_0 T_p(f_0)} \tilde{x}_0(t - T_g(f_0)) \\
 &= \frac{|A|}{R} e^{j(\varphi - (2\pi f_0)^2 \frac{R}{g})} \frac{c}{2} e^{-\kappa(t - 4\pi f_0 \frac{R}{g})} (t - 4\pi f_0 \frac{R}{g} + j) u(t - 4\pi f_0 \frac{R}{g})
 \end{aligned}$$

thus the narrowband output is

$$y(t) = 2 \operatorname{Re} \left[\tilde{y}_0(t) e^{j 2\pi f_0 t} \right]$$

when $2\pi f_0 \frac{R}{g} = \frac{1001}{2f_0} \Rightarrow f_0^2 = \frac{g \cdot 1001}{4\pi R}$

$T_g(f_0) = 4\pi f_0 \frac{R}{g} = \frac{1001}{f_0}$ as $f_0 \rightarrow \infty \Rightarrow T_g \rightarrow 0$
 $f_0 \rightarrow 0 \Rightarrow T_g \rightarrow \infty$

so for high frequencies group delay may be neglected but not for low frequencies.

$T_p(f_0) = \frac{-\varphi}{2\pi f_0} + 2\pi f_0 \frac{R}{g} = \frac{1}{f_0} \left(\frac{1}{2} - \frac{\varphi}{2\pi} \right)$

so $2\pi f_0 T_p(f_0) = 2\pi \left(\frac{1}{2} - \frac{\varphi}{2\pi} \right) = \pi - \varphi$

and $e^{-j2\pi f_0 T_p(f_0)} = e^{j(\varphi - \pi)} = -e^{j\varphi}$

e) Note as t increases $x(t) \sim e^{-\kappa t}$ decreases exponentially with time. Assuming that the effective duration T of $x(t)$ is when $e^{-\kappa t} > e^{-1}$ so $T \approx \frac{1}{\kappa}$ then the bandwidth is approximately $\omega \approx \kappa$.

From part (b) we obtained a constraint for the bandwidth in order to neglect dispersion thus:

$\omega^2 \leq \frac{g}{16\pi R} \Rightarrow \kappa^2 \leq \frac{g}{16\pi R}$