

# Quiz #3 solutions.

## Problem 1

i)  $\hat{S}_x(f) = \frac{|X_w(f)|^2}{T_L}$  is our spectral estimation

function compute the mean:

$$E[\hat{S}_x(f)] = \frac{E[|X_w(f)|^2]}{T_L} =$$

$$= \frac{1}{T_L} \int_{-T_L/2}^{T_L/2} dt_1 \int_{-T_L/2}^{T_L/2} dt_2 w(t_1) w(t_2) \underbrace{E[x(t_1) x^*(t_2)]}_{R_x(t_1-t_2)} e^{-j2\pi f(t_1-t_2)}$$

$$= \frac{1}{T_L} \int_{-\infty}^{\infty} S_x(u) \int_{-T_L/2}^{T_L/2} w(t_1) e^{j2\pi(f-u)t_1} dt_1 \int_{-T_L/2}^{T_L/2} w(t_2) e^{-j2\pi(u-f)t_2} dt_2$$

$R_x(t_1-t_2) = \int S_x(u) e^{j2\pi u(t_1-t_2)} du$

$$= \frac{1}{T_L} \int_{-\infty}^{\infty} S_x(u) \bar{W}(f-u) \bar{W}(u-f) du \quad \text{with real } \rightarrow \bar{W}(f) = \bar{W}^*(f)$$

$$= \frac{1}{T_L} \int_{-\infty}^{\infty} S_x(u) |\bar{W}(f-u)|^2 du$$

assuming that  $S_x(f)$  is "smooth" across the bandwidth of  $\bar{W}(f)$  then

$$E[\hat{S}_x(f)] = \frac{1}{T_L} S_x(f) \int_{-\infty}^{\infty} |\bar{W}(u)|^2 du$$

for unbiased estimate we require

$$\int_{-\infty}^{\infty} |\bar{W}(u)|^2 du = \int_{-T_L/2}^{T_L/2} w^2(t) dt = T_L$$

For the Hanning taper I require

$$\int_{-T/2}^{T/2} a^2 \cos^2\left(\frac{nt}{T}\right) dt = T_L \Rightarrow$$

$$\int_{-T/2}^{T/2} \frac{a^2}{4} \left(1 + \cos\left(\frac{2nt}{T}\right)\right)^2 dt = \frac{a^2}{4} \int_{-T/2}^{T/2} \left(1 + \cos^2\left(\frac{2nt}{T}\right) + \underbrace{2\cos\left(\frac{2nt}{T}\right)}_{\int dt=0}\right) dt$$

$$= \frac{a^2}{4} \left[ T_L + \frac{1}{2} \int_{-T/2}^{T/2} \underbrace{1 + \cos\left(\frac{4nt}{T}\right)}_{\int dt=0} dt \right] = \frac{a^2}{4} \left( T_L + \frac{T_L}{2} \right)$$

$$= \frac{a^2}{4} \frac{3T_L}{2} = T_L \Rightarrow a = \sqrt{\frac{8}{3}}$$

ii)  $\sigma_{\hat{S}_x(f)}^2 = E\left[|\hat{S}_x(f)|^2\right] - \left|E[\hat{S}_x(f)]\right|^2$

$$E\left[|\hat{S}_x(f)|^2\right] = E\left[\frac{|X_w(f)|^4}{T_L^2}\right]$$

since  $X_w(f)$  is complex Gaussian r.v. +  $f$  with zero mean we can invoke the product moment theorem for Gaussians so

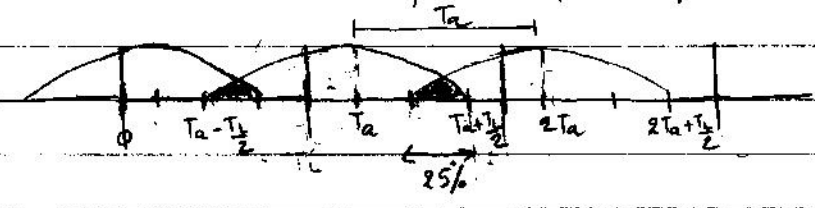
$$E\left[\frac{|X_w(f)|^4}{T_L^2}\right] = \frac{2}{T_L^2} E\left[|X_w(f)|^2\right]^2$$

Hence,  $\sigma_{\hat{S}_x(f)}^2 = \frac{2}{T_L^2} E\left[|X_w(f)|^2\right]^2 - \left(\frac{E\left[|X_w(f)|^2\right]}{T_L}\right)^2$

$$= \frac{E\left[|X_w(f)|^2\right]^2}{T_L^2} \stackrel{\text{part (i)}}{=} \frac{S_x(f) T_L^2}{T_L^2} = S_x^2(f)$$

Thus windowing doesn't mitigate the variance.

iii) Below is an example of 25% overlap



no overlap  $\Rightarrow T_a = T_L$

with overlap  $\Rightarrow A = T_a + \frac{T_L}{2} - (2T_a - \frac{T_L}{2}) = T_L - T_a = T_L(1 - T_a/T_L) = T_L(1 - \alpha)$

compute :  $E[\hat{S}_x^h(f) \hat{S}_x^m(f)] =$

$$\frac{1}{T_L^2} E[X_w^n(f) X_w^{h*}(f) X_w^m(f) X_w^{m*}(f)] \quad \text{product moment thm}$$

$$= \frac{1}{T_L^2} \left[ E[X_w^n(f) X_w^{n*}(f)] E[X_w^m(f) X_w^{m*}(f)] + E[X_w^n(f) X_w^{m*}(f)] E[X_w^{n*}(f) X_w^m(f)] \right]$$

$$= \dots \left[ \frac{E[|X_w^n(f)|^2]}{T_L} \frac{E[|X_w^m(f)|^2]}{T_L} + \frac{|E[X_w^n(f) X_w^{m*}(f)]|^2}{T_L^2} \right] \quad \text{①}$$

$S_x^2(f)$

need to know:  $E[X_w^n(f) X_w^{m*}(f)] =$

$$\int_{nT_a - T_L/2}^{nT_a + T_L/2} dt_1 \int_{mT_a - T_L/2}^{mT_a + T_L/2} dt_2 w(t_1 - nT_a) w(t_2 - mT_a) E[X(t_1) X^*(t_2)] e^{-j2\pi f(t_1 - t_2)}$$

$$R_x(t_1 - t_2) = \int_{-\infty}^{\infty} S_x(u) e^{j2\pi u(t_1 - t_2)} du$$

$$= \int_{-\infty}^{\infty} S_x(u) \int_{nT_a - T_L/2}^{nT_a + T_L/2} w(t_1 - nT_a) e^{j2\pi t_1(f-u)} dt_1 \int_{mT_a - T_L/2}^{mT_a + T_L/2} w(t_2 - mT_a) e^{-j2\pi t_2(u-f)} dt_2$$

$$= \int_{-\infty}^{\infty} S_x(u) \bar{W}(f-u) e^{j2\pi(f-u)nT_a} \bar{W}(u-f) e^{j2\pi(u-f)mT_a} du$$

$$= \int_{-\infty}^{\infty} S_x(u) |W(f-u)|^2 e^{j2\pi(f-u)T_a(n-m)} du \quad \text{S_x(f) "smooth"}$$

$$= S_x(f) \int_{-\infty}^{\infty} |W(u)|^2 e^{j2\pi u T_a(n-m)} du$$

I want to compute the variance of the estimate

$$\hat{S}_x(f) = \frac{1}{L} \sum_{n=1}^L \hat{S}_x^n(f)$$

$$\sigma_{\hat{S}_x(f)}^2 = \frac{1}{L^2} E \left[ \left( \sum_{n=1}^L \hat{S}_x^n(f) \right)^2 \right] = \frac{1}{L^2} E \left[ \sum_{n=1}^L \hat{S}_x^n(f) \right]^2$$

$$= \frac{1}{L^2} \sum_{n=1}^L \sum_{m=1}^L E \left[ \hat{S}_x^n(f) \hat{S}_x^m(f) \right] = \frac{1}{L^2} \left[ \sum_{n=1}^L \underbrace{E \left[ \hat{S}_x^n(f) \right]}_{S_x(f)} \right]^2$$

eq. 1

$$= \frac{1}{L^2} \sum_n \sum_m \cancel{S_x^n(f)} + \frac{1}{L^2} \sum_n \sum_m \frac{1}{T_L} \left| E \left[ X_w^n(f) X_w^{m*}(f) \right] \right|^2 - \cancel{S_x(f)^2}$$

$$\Rightarrow \sigma_{\hat{S}_x(f)}^2 = \frac{1}{L^2} \frac{1}{T_L^2} \sum_n \sum_m S_x^2(f) \left| \int_{-\infty}^{\infty} |W(u)|^2 e^{j2\pi u T_L(n-m)} du \right|^2$$

if we define  $p(n-m) \triangleq \frac{1}{T_L} \int_{-\infty}^{\infty} |W(u)|^2 e^{j2\pi u T_L(n-m)} du$

=  $\int_{-\infty}^{\infty} |W(u)|^2 du$  for unbiased estimate

then  $p(n-m) \triangleq \int_{-\infty}^{\infty} |W(u)|^2 e^{j2\pi u T_L(n-m)} du$

$\int_{-\infty}^{\infty} |W(u)|^2 du$  from Cauchy-Schwarz inequality

Note that  $|p(x)| \leq 1$ . Also we assume that for  $|n-m| > 1 \Rightarrow p(x) = 0$  because  $T_L \gg$  correlation scale of  $x(t)$ , so segments that do not overlap are uncorrelated in time (this assumption can be tricky in practice)

Hence I can write  $\frac{\sigma^2}{S_x^2(f)}$  in matrix form

$$\frac{\sigma^2}{S_x^2(f)} = \frac{1}{L^2} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}^T \begin{bmatrix} 1 & |p(x)|^2 & 0 & 0 \\ |p(x)|^2 & \ddots & \ddots & \ddots \\ 0 & \ddots & \ddots & 1 \\ 0 & \ddots & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$\text{so } \frac{\sigma^2}{S_x^2(f)} = \frac{1}{L^2} (L \cdot 1 + 2(L-1) |p(x)|^2)$$

$$L \gg 1 \Rightarrow \frac{1}{L^2} (L + 2L |p(x)|^2) = \frac{1 + 2 |p(x)|^2}{L}$$

$$|p(x)|^2 = \cos^2\left(\frac{\pi}{2}x\right) \Rightarrow \frac{1}{L} \left(1 + 2 \cos^2\left(\frac{\pi}{2}x\right)\right) \stackrel{L = \frac{T}{T_c \cdot x}}{=} \frac{T}{T_c \cdot x} \left(1 + 2 \cos^2\left(\frac{\pi}{2}x\right)\right)$$

I want to minimize  $\frac{\sigma^2}{S_x^2(f)}$  so

$$\frac{d}{dx} \frac{T}{T_c} \left(1 + 2 \cos^2\left(\frac{\pi}{2}x\right)\right) = 0$$

$$\Rightarrow \frac{T_c}{T} \left(1 + 2 \cos^2\left(\frac{\pi}{2}x\right)\right) + \frac{x \cdot T_c}{T} \left(4 \cos\left(\frac{\pi}{2}x\right) \sin\left(\frac{\pi}{2}x\right) \frac{\pi}{2}\right) = 0$$

$$\Rightarrow 1 + 2 \cos^2\left(\frac{\pi}{2}x\right) - \pi x \sin(\pi x) = 0 \Rightarrow$$

$$2 + \cos(\pi x) = \pi x \sin(\pi x)$$

The above equation determines optimum overlap for minimizing the variance.

## Problem 2

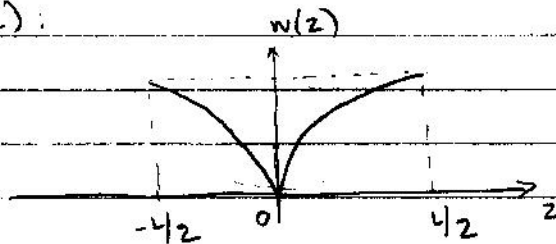
i) From the MRA constraint we have:

$$\int_{-L/2}^{L/2} w(z) dz = 1 \quad (\text{I am assuming broadside steering})$$

$$\text{so } \int_{-L/2}^{L/2} a \sin^2 \frac{\pi z}{L} dz = \frac{a}{2} \int_{-L/2}^{L/2} \underbrace{1 - \cos \frac{2\pi z}{L}}_{\int dz \rightarrow 0} dz =$$

$$= \frac{aL}{2} = 1 \Rightarrow \boxed{a = \frac{2}{L}}$$

Plot of  $w(z)$ :



frequency wavenumber response function:

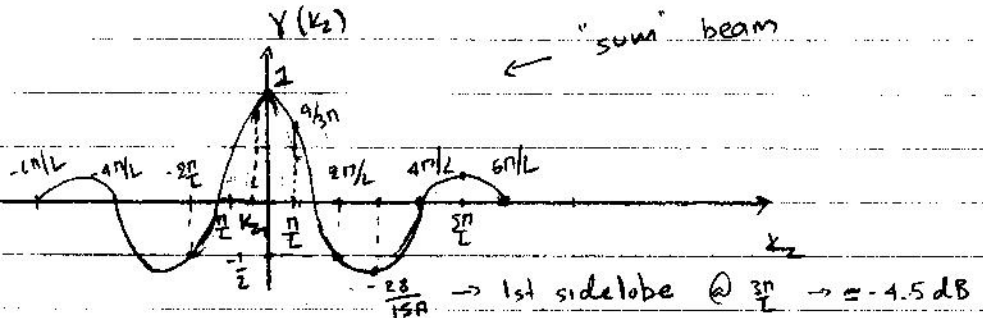
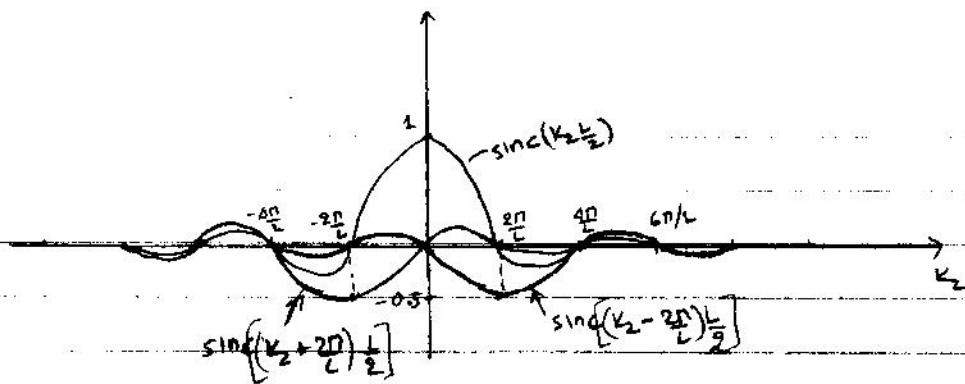
$$Y(k_2) = \int_{-L/2}^{L/2} w(z) e^{-jk_2 z} dz = \int_{-L/2}^{L/2} a \sin^2 \frac{\pi z}{L} e^{-jk_2 z} dz$$

$$= \frac{a}{2} \int_{-L/2}^{L/2} e^{-jk_2 z} dz - \frac{a}{2} \int_{-L/2}^{L/2} \cos \frac{2\pi z}{L} e^{-jk_2 z} dz$$

$$= \frac{a}{2} L \operatorname{sinc}\left(k_2 \frac{L}{2}\right) - \frac{a}{2} \frac{1}{2\pi} \left[ L \operatorname{sinc}\left(\frac{k_2 L}{2}\right) + \left[ \pi \delta\left(k_2 - \frac{2\pi}{L}\right) + \pi \delta\left(k_2 + \frac{2\pi}{L}\right) \right] \right]$$

$aL=2$

$$= a \operatorname{sinc}\left(k_2 \frac{L}{2}\right) - \frac{1}{2} \operatorname{sinc}\left[\left(k_2 - \frac{2\pi}{L}\right) \frac{L}{2}\right] - \frac{1}{2} \operatorname{sinc}\left(k_2 + \frac{2\pi}{L}\right) \frac{1}{2}$$



Note that the mainlobe is narrower than that of a uniform weighting aperture at the expense of higher sidelobes.

$$\begin{aligned}
 \text{ii)} \quad \int_{-L/2}^{L/2} w^2(z) dz &= \int_{-L/2}^{L/2} a^2 \sin^4 \frac{\pi z}{L} dz = \frac{a^2}{4} \int_{-L/2}^{L/2} (1 - \cos(2\pi z/L))^2 dz \\
 &= \frac{a^2}{4} \int_{-L/2}^{L/2} 1 + \cos^2(2\pi z/L) - 2 \cos(2\pi z/L) dz = \\
 &= \frac{a^2}{4} L + \frac{a^2}{8} \int_{-L/2}^{L/2} 1 - \cos(4\pi z/L) dz = \frac{a^2}{4} L + \frac{a^2}{8} L \\
 &= \frac{3a^2 L}{8} = \frac{3}{2} L
 \end{aligned}$$

$$\text{Hence } NA_w = \frac{1}{L \frac{3}{2} L} = \frac{2}{3} < 1 \quad (\text{for uniform weighting})$$

The Hanning taper is:

$$h(z) = \begin{cases} a \cos^2\left(\frac{\pi z}{L}\right) & |z| \leq \frac{L}{2} \\ 0 & |z| > \frac{L}{2} \end{cases}$$

Similarly we can prove that  $a = \frac{2}{L}$  (MRA

condition) and  $\int_{-L/2}^{L/2} h^2(z) dz = \frac{3}{2L}$  resulting

the same noise enhancement. Obviously, tapers

having the same  $\int_{-L/2}^{L/2} w^2(z) dz$  will yield the

same NAW.

ii) In this case the frequency-wavenumber

response function is:

$$\begin{aligned} Y(k_z) &= - \int_{-L/2}^0 \sin^2\left(\frac{\pi z}{L}\right) e^{-jk_z z} dz + \int_0^{L/2} \sin^2\left(\frac{\pi z}{L}\right) e^{-jk_z z} dz \\ &= -\frac{1}{2} \int_{-L/2}^0 (1 - \cos\left(\frac{2\pi z}{L}\right)) e^{-jk_z z} dz + \frac{1}{2} \int_0^{L/2} (1 - \cos\left(\frac{2\pi z}{L}\right)) e^{-jk_z z} dz \\ &= -\frac{1}{2} \int_0^{L/2} (1 - \cos\left(\frac{2\pi z}{L}\right)) e^{jk_z z} dz + \frac{1}{2} \int_0^{L/2} (1 - \cos\left(\frac{2\pi z}{L}\right)) e^{-jk_z z} dz \end{aligned}$$

$$\underline{\underline{a - a^* = 2j \operatorname{Im}(a)}} \quad 2j \operatorname{Im} \left[ \frac{1}{2} \int_0^{L/2} (1 - \cos\left(\frac{2\pi z}{L}\right)) e^{-jk_z z} dz \right]$$



(4)

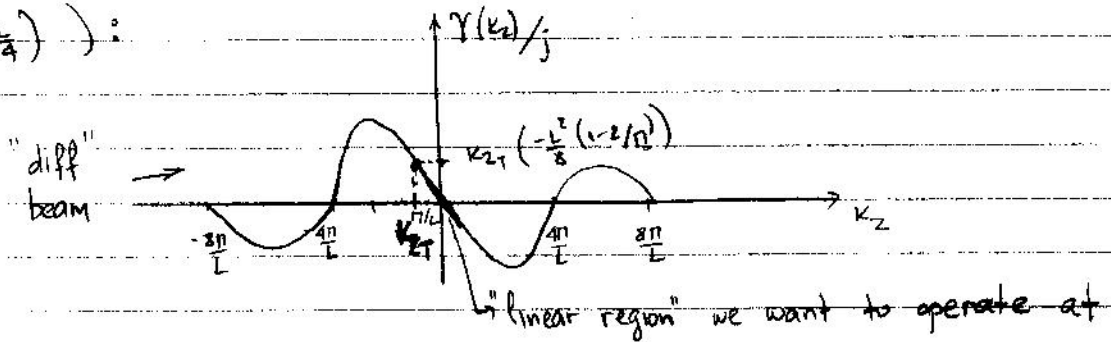
$$\begin{aligned}
 &= j I_m \left[ \text{F.T.} \left[ \begin{array}{c} \text{rectangle} \\ 0 \quad L/2 \end{array} \right] - \text{F.T.} \left[ \begin{array}{c} \text{rectangle} \\ 0 \quad L/2 \end{array} \cdot \cos\left(\frac{2\pi z}{L}\right) \right] \right] \\
 &= j I_m \left[ e^{-j k_z L/4} \frac{L}{2} \text{sinc}\left(\frac{k_z L}{4}\right) - e^{j k_z L/4} \frac{L}{2} \text{sinc}\left(\frac{k_z L}{4}\right) * \left( \pi \delta\left(k_z - \frac{2\pi}{L}\right) + \pi \delta\left(k_z + \frac{2\pi}{L}\right) \right) \right] \\
 &= j \sin\left(-k_z \frac{L}{4}\right) \left[ \frac{L}{2} \text{sinc}\left(\frac{k_z L}{4}\right) - \frac{L}{4} \text{sinc}\left(\left(k_z - \frac{2\pi}{L}\right) \frac{L}{4}\right) - \frac{L}{4} \text{sinc}\left(\left(k_z + \frac{2\pi}{L}\right) \frac{L}{4}\right) \right] \\
 &= -j \frac{L}{2} \sin\left(k_z \frac{L}{4}\right) \left[ \text{sinc}\left(k_z \frac{L}{4}\right) - \frac{1}{2} \text{sinc}\left(\left(k_z - \frac{2\pi}{L}\right) \frac{L}{4}\right) - \frac{1}{2} \text{sinc}\left(\left(k_z + \frac{2\pi}{L}\right) \frac{L}{4}\right) \right]
 \end{aligned}$$

Note that  $\left. \frac{dY(k_z)}{dk_z} \right|_{k_z=0} = -j \frac{L}{2} \frac{L}{4} \left( 1 - \frac{1}{2} \frac{1}{\frac{\pi}{2}} - \frac{1}{2} \frac{1}{\frac{\pi}{2}} \right) =$

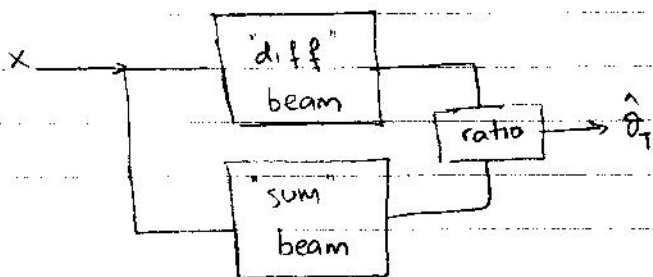
$$= -j \frac{L^2}{8} \left( 1 - \frac{2}{\pi} \right)$$

so the slope is negative which means that the

plot of  $Y(k_z)$  looks like (odd function due to  $\sin(k_z \frac{L}{4})$ ):



Consider the following structure:



(5)

This structure estimates the angle of arrival  $\theta_T$

of a target measured off broadside without electronically steering.

Suppose that  $\theta_T$  small  $\Rightarrow \sin \theta_T \approx \theta_T \Rightarrow$

$$k_{zT} = \frac{2\pi}{\lambda} \sin \theta_T \approx \frac{2\pi}{\lambda} \theta_T \quad \text{The "diff" beam}$$

imposes a gain of  $k_{zT} \cdot \left. \frac{dY(k_z)}{dk_z} \right|_{k_z=0}$  to the incoming signal assuming we operate in the linear region while the "sum" beam imposes a gain

$\approx 0$  dB. Forming the ratio the unknown amplitude

is cancelled out thus computing the angle of arrival:

$$\text{Ratio} = \frac{k_{zT} \cdot \left( -\frac{L^2}{8} \left( 1 - \frac{2}{\pi} \right) \right)}{1} \approx$$

$$\frac{2\pi}{\lambda} \theta_T \left( -\frac{L^2}{8} \left( 1 - \frac{2}{\pi} \right) \right) \Rightarrow \theta_T \text{ is known.}$$

In order to assume that the "sum" beam puts no gain

note that we are in the "linear region" for this condition

$$\text{on } x \quad k_{zT} < \frac{\pi}{L} \Leftrightarrow \frac{2\pi}{\lambda} \sin \theta_T < \frac{\pi}{L} \Rightarrow \sin \theta_T < \frac{\lambda}{2L}$$

$$\approx \boxed{\theta_T < \frac{\lambda}{2L}} \quad \left( \text{half the broadside resolution} \right) \\ \text{of a uniformly weighted aperture}$$